

ParK: Sound and Efficient Kernel Ridge Regression by Feature Space Partitions

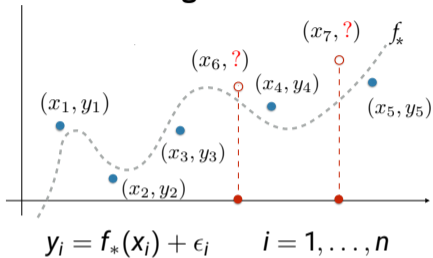
Luigi Carratino¹ Stefano Vigogna¹ Daniele Calandriello² Lorenzo Rosasco^{1,3}

¹MaLGA - DIBRIS, University of Genova ²DeepMind Paris ³CBMM, MIT & IIT

NeurIPS 2021

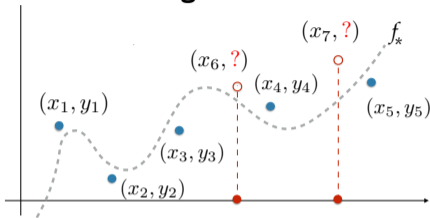
Kernel ridge regression

Regression

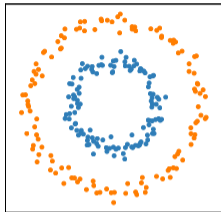


Kernel ridge regression

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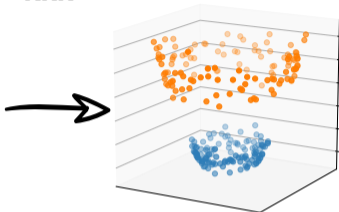


$$y_i = f_*(x_i) + \epsilon_i \quad i = 1, \dots, n$$



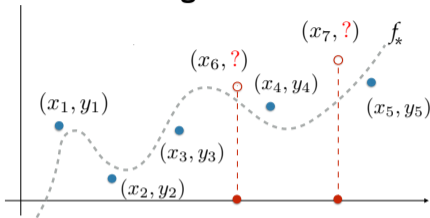
$$\min_{f \in \mathcal{H}} \frac{1}{n} \sum_{i=1}^n |f(x_i) - y_i|^2 + \lambda \|f\|_{\mathcal{H}}^2$$

KRR



Kernel ridge regression

Regression



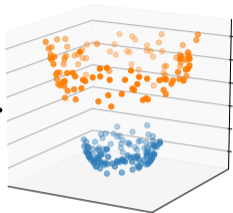
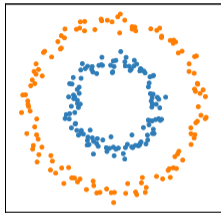
$$y_i = f_*(x_i) + \epsilon_i \quad i = 1, \dots, n$$

Solution

$$\hat{K} \mathbf{c} = \hat{\mathbf{y}}$$

$$\hat{f}_\lambda(x) = \sum_{i=1}^n c_i K(x_i, x) \quad \mathbf{c} = (\hat{K} + \lambda \mathbf{I})^{-1} \hat{\mathbf{y}}$$

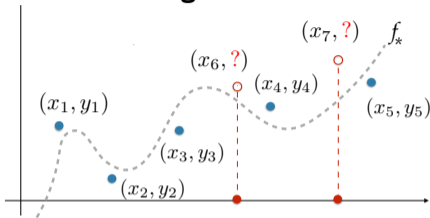
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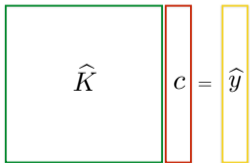
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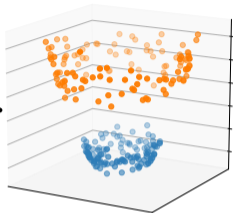
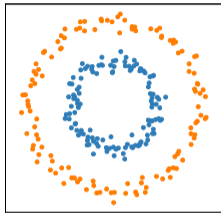
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KRR



$$\min_{f \in \mathcal{H}} \frac{1}{n} \sum_{i=1}^n |f(x_i) - y_i|^2 + \lambda \|f\|_{\mathcal{H}}^2$$

Complexity

- Statistics: **optimal**
- Computations: $\mathcal{O}(n^3)$

Accelerated KRR

Naive $\mathcal{O}(n^3)$

$$\hat{K} c = \hat{y}$$

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Iterating $\mathcal{O}(tn^2)$

$$c_{t+1} = c_t - \hat{K} c_t + \hat{y}$$

Accelerated KRR

Naive $\mathcal{O}(n^3)$

$$\widehat{K} \begin{matrix} | \\ c \\ | \end{matrix} = \begin{matrix} | \\ \widehat{y} \\ | \end{matrix}$$

Iterating $\mathcal{O}(tn^2)$

$$\begin{matrix} | \\ c_{t+1} \\ | \end{matrix} = \begin{matrix} | \\ c_t \\ | \end{matrix} - \begin{matrix} \widehat{K} \\ | \\ c_t \\ | \end{matrix} + \begin{matrix} | \\ \widehat{y} \\ | \end{matrix}$$

Sketching $\mathcal{O}(M^2n)$

$$\begin{matrix} \widehat{K}_{nM} \\ | \\ c \\ | \end{matrix} = \begin{matrix} | \\ \widehat{y} \\ | \end{matrix}$$

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Sketching $\mathcal{O}(M^2n)$

$$\widehat{K}_{nM} \begin{matrix} | \\ c \\ | \end{matrix} = \begin{matrix} | \\ \widehat{y} \\ | \end{matrix}$$

Splitting $\mathcal{O}((n/Q)^3)$

$$\begin{matrix} \widetilde{K}_1 \\ \widetilde{K}_2 \\ \vdots \\ \widetilde{K}_Q \end{matrix} \begin{matrix} | \\ c_1 \\ | \\ | \\ c_2 \\ | \\ \vdots \\ | \\ c_Q \\ | \end{matrix} = \begin{matrix} | \\ \widetilde{y}_1 \\ | \\ | \\ \widetilde{y}_2 \\ | \\ \vdots \\ | \\ \widetilde{y}_Q \\ | \end{matrix}$$

Combined methods

GD, CG	Iterating	$\mathcal{O}(tn^2)$
Nyström ^a , RF ^b	Sketching	$\mathcal{O}(M^2n)$
D&C ^c , DC-KRR ^d	Splitting	$\mathcal{O}((n/Q)^3)$

a. [Williams, Seeger, '00]

b. [Rahimi, Recht, '09]

c. [Zhang, Duchi, Wainwright, '15]

d. [Tandon, Si, Ravikumar, Dhillon, '16]

Combined methods

			FALKON ^e
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Combined methods

			FALKON ^e	LocalNysation ^f
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Combined methods

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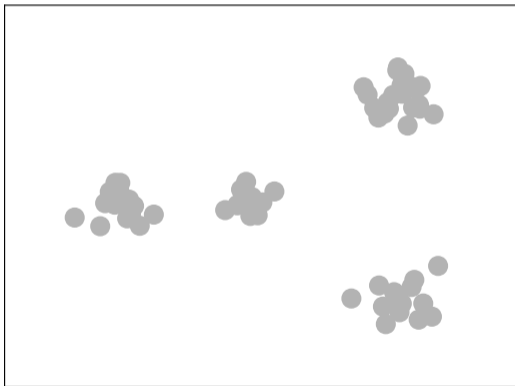
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ParK, a new large-scale KRR solver that

- combines the computational benefits of iterations, sketching and splitting
- preserves the generalization power under suitable partitions
- introduces a new principled partition scheme for kernel methods

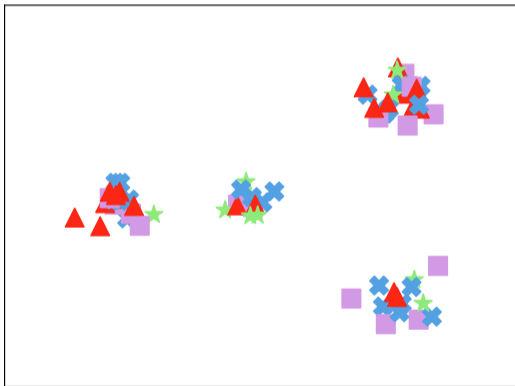
Data splitting vs space partitions

Splitting



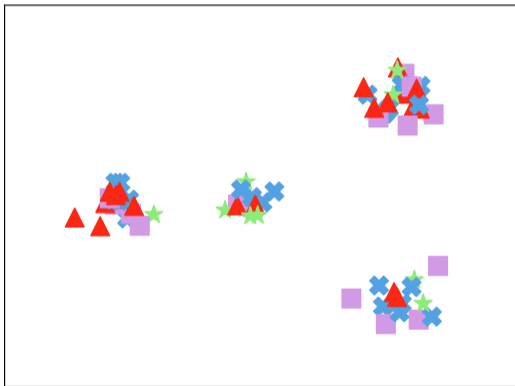
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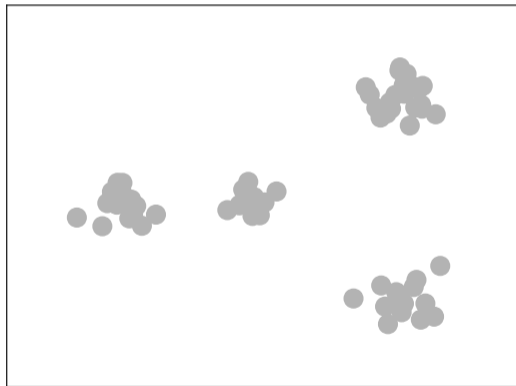


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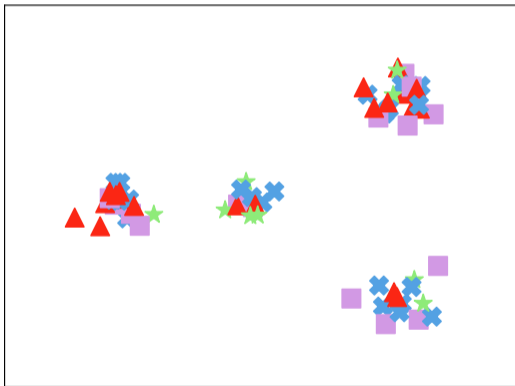


Partitioning

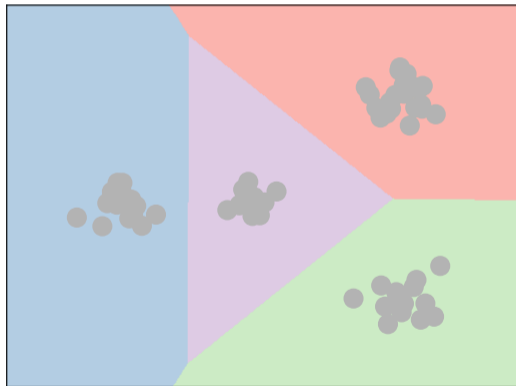


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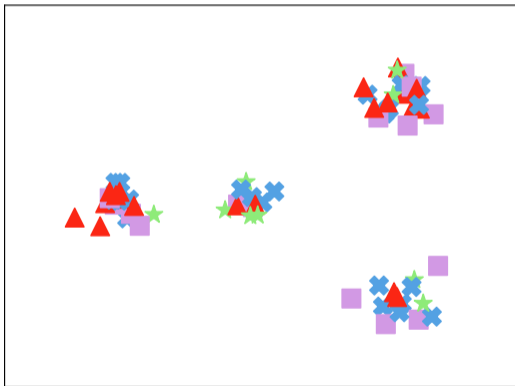


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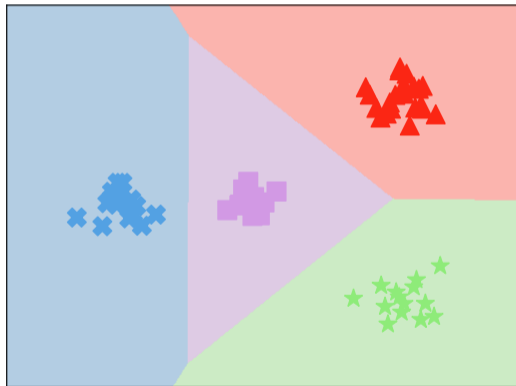


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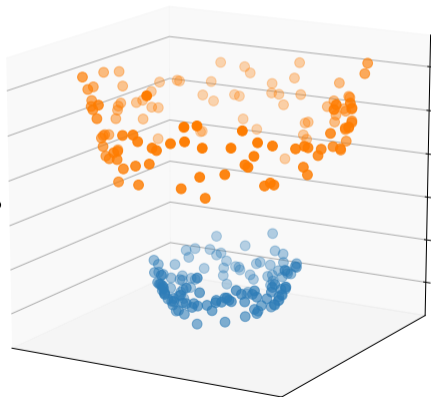
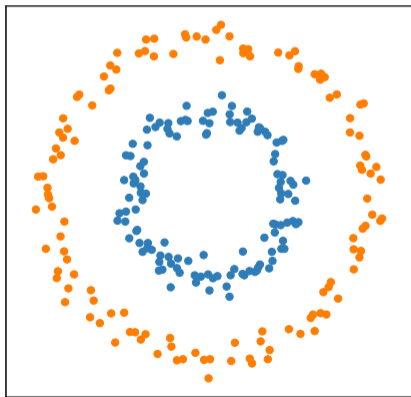


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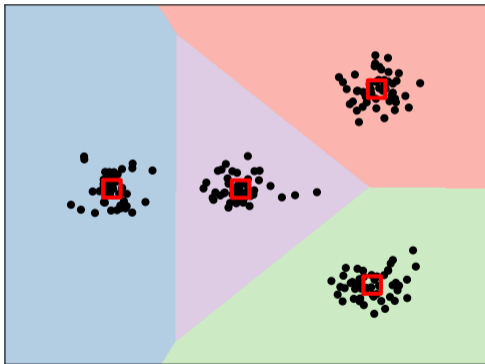
Input vs feature space partitions

$$\mathcal{X} \xrightarrow{\phi} \mathcal{H}$$



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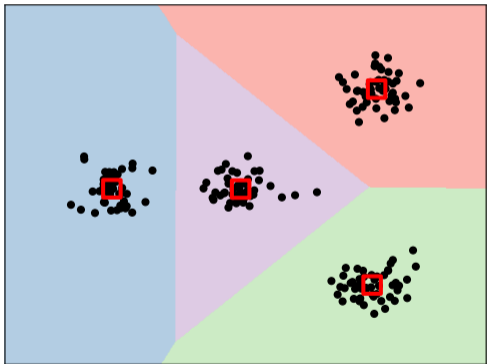
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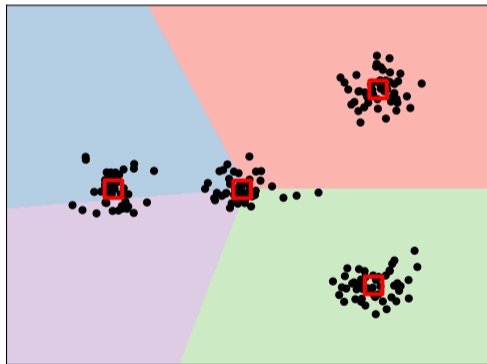
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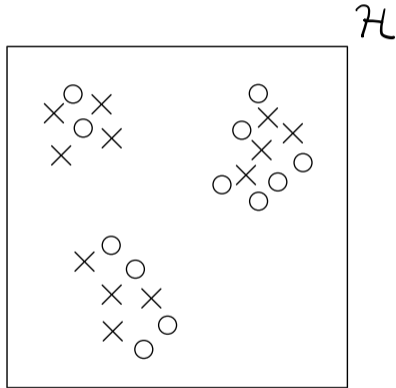


$$\|\phi(\mathbf{x}_1) - \phi(\mathbf{x}_2)\|_{\mathcal{H}}^2 = 2 - 2 \frac{\langle \mathbf{x}_1, \mathbf{x}_2 \rangle}{\|\mathbf{x}_1\| \|\mathbf{x}_2\|}$$

Park

1. partition the feature space into Q Voronoi cells:

$$\mathcal{H} = \bigcup_{q=1}^Q V_q$$

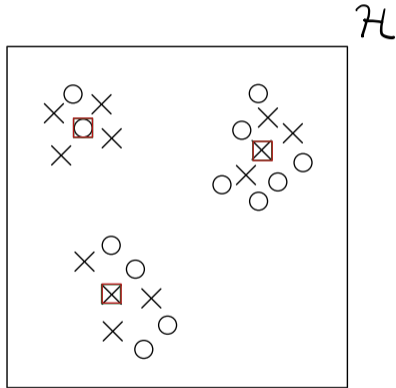


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$\phi(\mathbf{c}_k)$

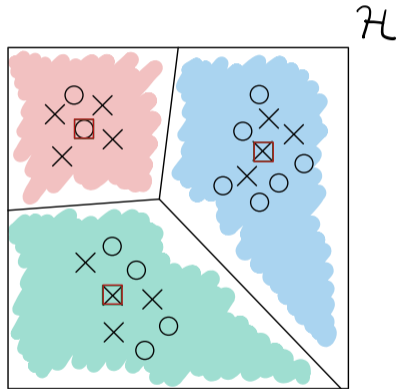


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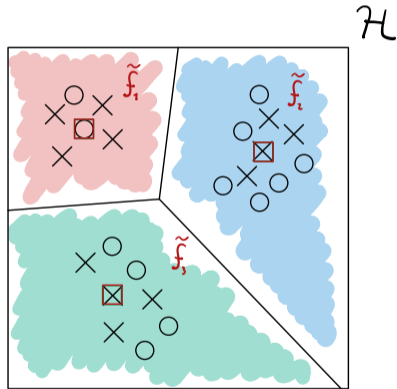
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2. solve (iterated, sketched) KRR locally on each cell:

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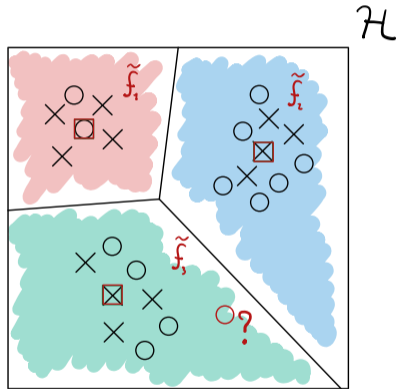
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3. **predict** new samples **on the corresponding cells**:

$$\hat{\mathbf{f}}(\mathbf{x}) = \tilde{\mathbf{f}}_q(\mathbf{x}) \quad \text{if } \phi(\mathbf{x}) \in V_q$$



Generalization

KRR generalization without partitioning $\|\hat{f} - f_*\|^2 \lesssim \lambda + \frac{d_{\text{eff}}(\lambda)}{n}$

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Theorem (Carratino, Vigogna, Calandriello, Rosasco '21)

Let $\theta = \min_{q \neq k} \angle(\mathcal{H}_q, \mathcal{H}_k)$ and $\lambda_q = \lambda n / \#V_q$. Then w.h.p.

$$\|\hat{f} - f_*\|^2 \lesssim (1 + Q^2 \cos(\theta))\lambda + \left(1 + \frac{\cos^2(\theta)}{\lambda}\right) \frac{d_{\text{eff}}(\lambda)}{n}$$

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When cells are orthogonal (i.e. $\mathcal{H} = \bigoplus_{q=1}^Q \mathcal{H}_q$ i.e. $\theta = \pi/2$) we recover $\|\hat{f} - f_*\|^2 \lesssim \lambda + \frac{d_{\text{eff}}(\lambda)}{n}$

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When $\cos(\theta) = \mathcal{O}(\min(1/Q^2, \lambda))$ we obtain $\|\hat{f} - f_*\|^2 \lesssim \mathcal{O}\left(\lambda + \frac{d_{\text{eff}}(\lambda)}{n}\right)$

Feature space Voronoi partitions

Voronoi centroids:

greedy select

$$c_{q+1} = \arg \max_{c \in \{x_i\}_{i=1}^n \setminus \{c_1, \dots, c_q\}} SC_q(c)$$

where $SC_q(c)$ is the **Schur complement** of $[K(c_k, c_h)]_{k,h=1}^q$ in $\begin{bmatrix} K(c, c) & K(c, c_k) \\ K(c, c_k)^\top & K(c_k, c_h) \end{bmatrix}$

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ParK complexity: $\mathcal{O}(Q^2 n \log(n) + \max_q t_q M_q n_q)$

Experiments

	TAXI $n \approx 10^9$				HIGGS $n \approx 10^7$			
	ERROR (RMSE)	TIME (MIN.)			ERROR (1-AUC)	TIME (SEC.)		
		INIT	TRAIN	TOTAL		INIT	TRAIN	TOTAL
PARK	312.0 ± 0.2	25 ± 1	39 ± 13	64 ± 13	0.182 ± 0.001	30 ± 2	474 ± 172	504 ± 172
FALKON	311.7 ± 0.1	-	-	120 ± 1	0.180 ± 0.001	-	-	715 ± 6
D&C-FALK	356.2 ± 0.2	-	-	14 ± 1	0.212 ± 0.000	-	-	50 ± 1
D&C	OUT OF MEMORY				OUT OF MEMORY			
	AIRLINE $n \approx 10^6$				AIRLINE-CLS $n \approx 10^6$			
	ERROR (MSE)	TIME (SEC.)			ERROR (C-ERR)	TIME (SEC.)		
		INIT	TRAIN	TOTAL		INIT	TRAIN	TOTAL
PARK	0.760 ± 0.005	6 ± 1	71 ± 9	77 ± 10	$31.5 \pm 0.2\%$	9 ± 1	55 ± 6	64 ± 6
FALKON	0.758 ± 0.005	-	-	334 ± 2	$31.5 \pm 0.2\%$	-	-	391 ± 5
D&C-FALK	0.834 ± 0.005	-	-	27 ± 1	$33.2 \pm 0.1\%$	-	-	20 ± 1
D&C	OUT OF MEMORY				OUT OF MEMORY			

Thank you!